

Cognitive Architecture Usability

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NASA Human Simulation Applications







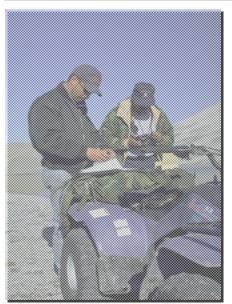


- Evaluating cockpit designs
- Planning crewed missions
- Artificial participants in training simulations
- Technology impact assessment

Problem:

Demand for human simulation models exceeds what modelers can supply with current tools









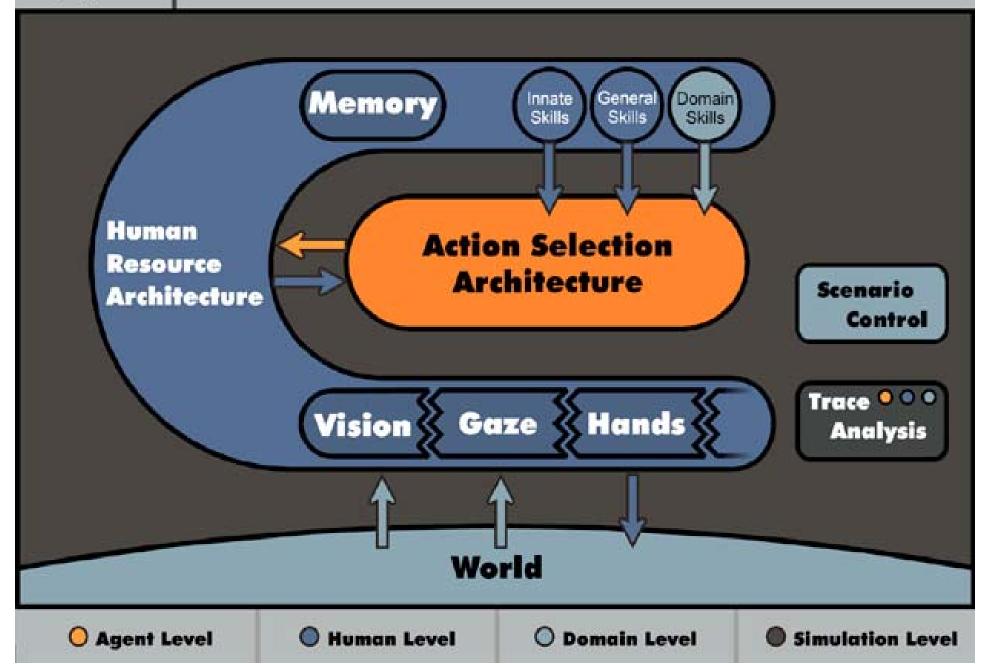
Challenges

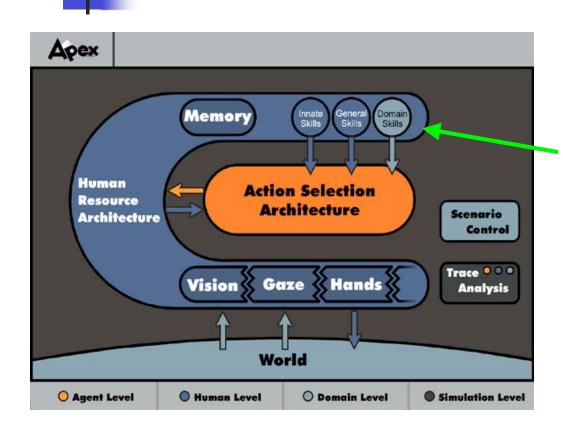
Goal in developing Apex has been to provide practical tool addressing 3 central challenges:

- Robust, intelligent behavior
- Valid, useful predictions
- Minimum time/expertise to build models





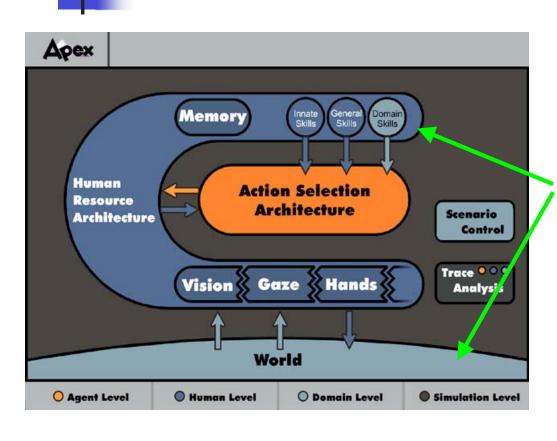




Usability efforts

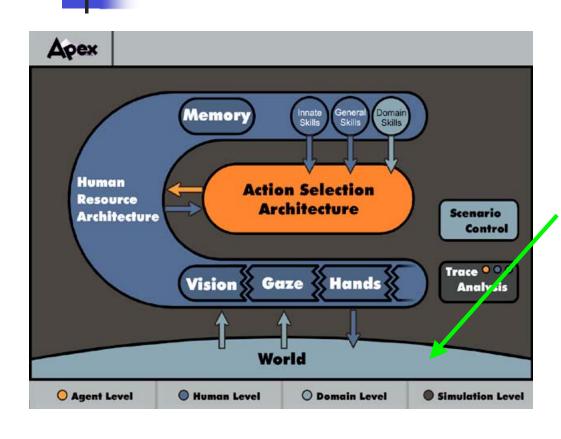
High-level language





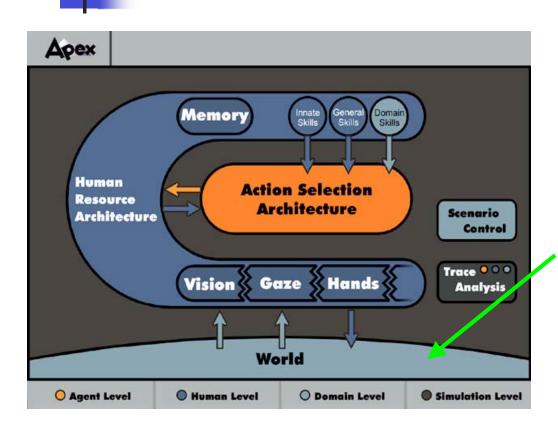
- High-level language
- Visualization/debug tools





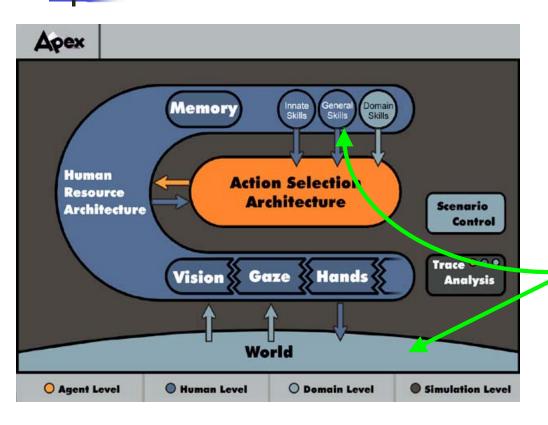
- High-level language
- Visualization/debug tools
- World modeling





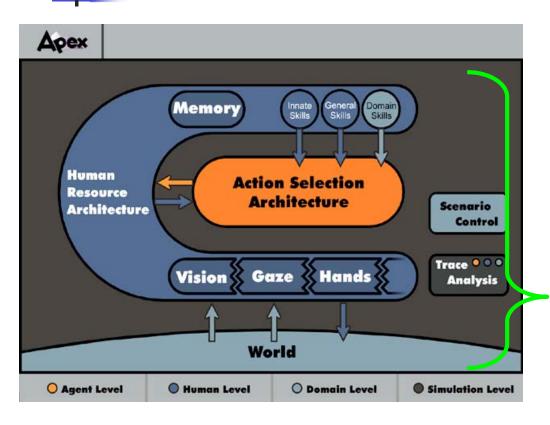
- High-level language
- Visualization/debug tools
- World modeling
- Interoperability





- High-level language
- Visualization/debug tools
- World modeling
 - Interoperability
 Reusable components





- High-level language
- Visualization/debug tools
- World modeling
- Interoperability
- Reusable components
- Distributed development



High-level behavior representation

Procedure Definition Language

```
concurrency
(procedure
                                        reactivity
   (index (hold-altitude using mcp))
                                        hierarchy
   (profile right-hand)

    contingency-handling

   (step s1 (clear right-hand))
   (step s2 (find-loc alt-hold-button => ?loc))
   (step s3 (press-button ?loc right-hand)
      (waitfor (empty right-hand)
                (location alt-hold-button ?loc)))
   (step end (terminate)
      (waitfor (illuminated alt-hold-button))
   (step aux1 (restart ?self)
      (waitfor (resumed ?self))))
```



Behavior representation: usability

Intuitive

(step s3 (stop) (waitfor (shape ?x light) (color ?x red))) conjunctive preconditions mutually constraining

Expressive

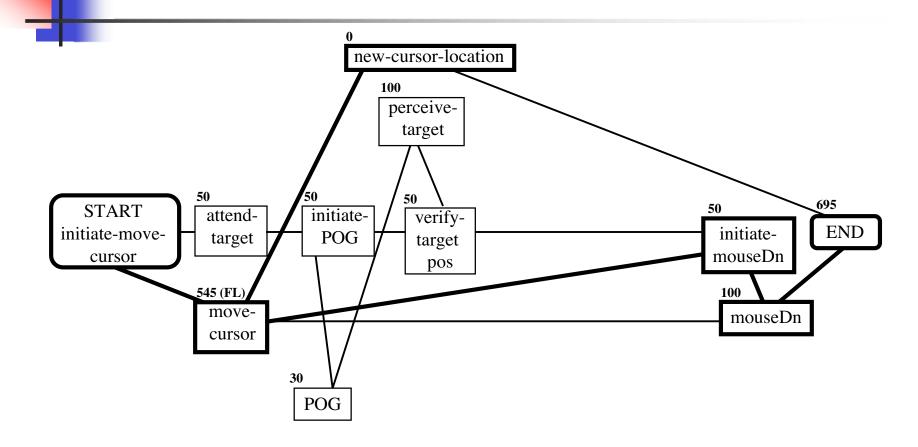
(step s4 (slow) (waitfor (color ?x green) then (color ?x yellow)) able to express temporal relations between preconditions

Compact

abbreviated form for sequential procedures

Evolves as users' needs become better understood



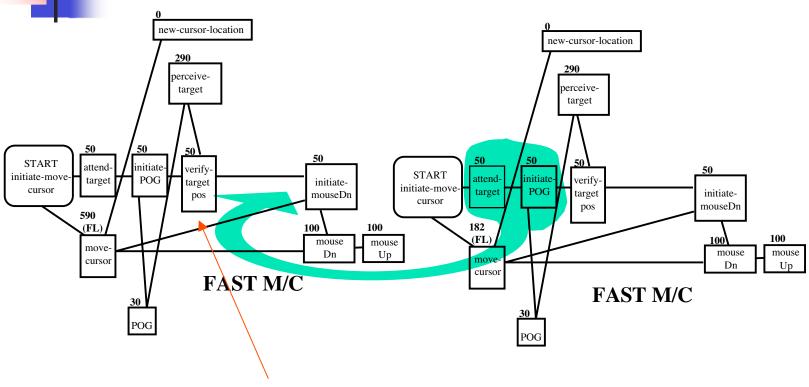


- from Gray and Boehm-Davis (2000)





Interleaving Templates



last vision action in the previous operator





CPM-GOMS requires that actions from templates earlier in a template sequence have priority in resource conflicts over activities from later templates.

Initial approach used the priority clause:

- determines how to resolve resource conflict
- globally scoped to allow comparison of any tasks

```
(step s2 (turn off alarm)
  (waitfor (on alarm))
  (priority 5))
```



Global scope of priority value assignments undesirable for CPM-GOMS representations

```
(procedure
                                        (procedure
 (index (get ?amt from atm))
                                         (index (init atm transaction))
 (step s1 (init atm transaction)
                                         (step s1 (insert card)
       (priority(3000))
                                            (priority (3200))
 (step s2 (withdraw ?amt))
                                         (step s2 (enter password)
       (priority 2000)
                                            (priority 3100)
 (step s3 (end atm transaction)
                                         (step s3 (terminate)
                                            (waitfor ?s2)))
       (priority 1000))
 (step s4 (terminate) (waitfor ?s3)))
                                           Requires modeler to
      Complex procedure to set
        priority values
                                           anticipate decomposition
```

Solution alternative mechanisms/syntax for resolving resource conflicts that is dynamically scoped

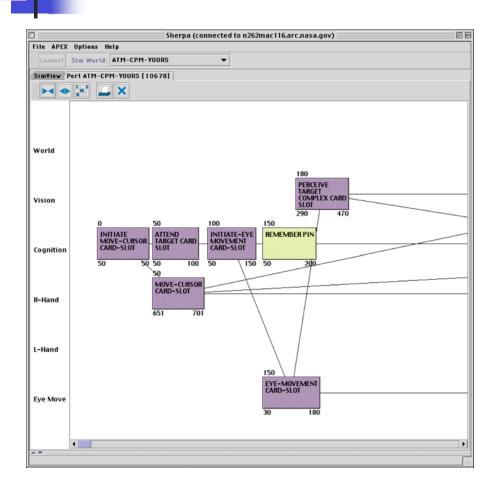




Abbreviation to further simplify syntax...



Visualizing and Debugging



Sherpa

- Simulation traces
- Physical environment
- PERT charts

VISTA

 Enhanced Sim Trace (2001 CMU student project)



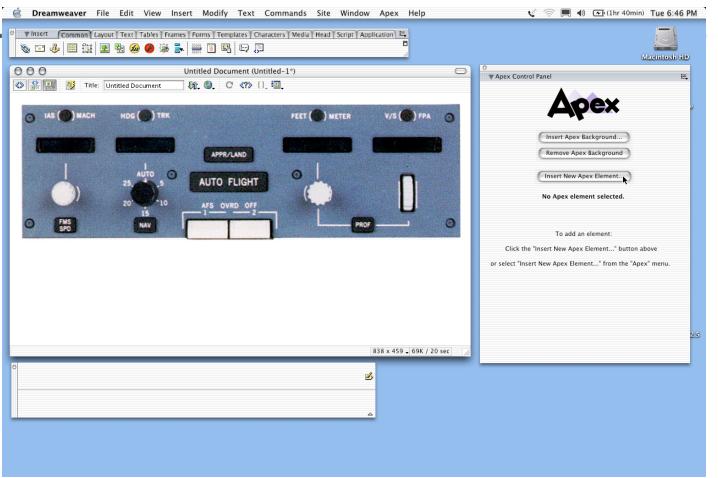
Specifying a Physical World Model

Time-consuming and error-prone when done by hand

```
C:\apex\worlds\atm-klm-world\initializeOrig.lisp
 2; ATM World Initialization
 3; positions and dimensions are in units of millimeters
   (in-package :common-lisp-user)
   (initialize-simulation
         ((bank (make-instance 'locale :name 'bank))
          (human (make-instance 'human :name 'agent :locale bank
                               :location '(0 0 22)))
          (atm (make-instance 'atm :name 'atm :locale bank
 13
                             :pos '(0 0) :dimensions '(182 164)))
          (money-slot (make-instance 'money-slot :name 'money-slot :locale bank
                                    :pos '(11 9) :dimensions '(98 2)))
          (screen (make-instance 'screen :name 'screen :locale bank
                                 :pos '(21 23) :dimensions '(108 68)))
 18
          (checking (make-instance 'button : name 'checking-key : locale bank
                                   :pos '(131 51) :dimensions '(15 11)))
          (withdraw (make-instance 'button :name 'withdraw-key :locale bank
                                   :pos '(131 66) :dimensions '(15 11)))
          (correct (make-instance 'button :name 'correct-key :locale bank
23
                                   :pos '(131 66) :dimensions '(15 11)))
          (no (make-instance 'button : name 'no-key : locale bank
                                   :pos '(131 81) :dimensions '(15 11)))
          (keypad (create-keypad '(43 104) '(13 11) '(4 2) 'down bank))
          (ok (make-instance 'button : name 'ok-key : locale bank
                                   :pos '(95 129) :dimensions '(15 11)))
          (card-slot (make-instance 'card-slot :name 'card-slot :locale bank
                                   :pos '(131 127) :dimensions '(43 2)))
31
          (mouse (create-mouse bank))
32
33
      ;; assemble top level objects
34
      (mapc #'assemble (list human atm))
      ;; assemble components of ATM
36
      (mapc #'(lambda (obj) (assemble obj :component-of atm))
```

Specifying a Physical World Model

Easy with drag-and-drop interface



CMU 2002 student project







Interoperability

In search of a general solution



Apex pilot flies an F-16 over NASA Ames

Apex interops with:
Riptide
X-Plane

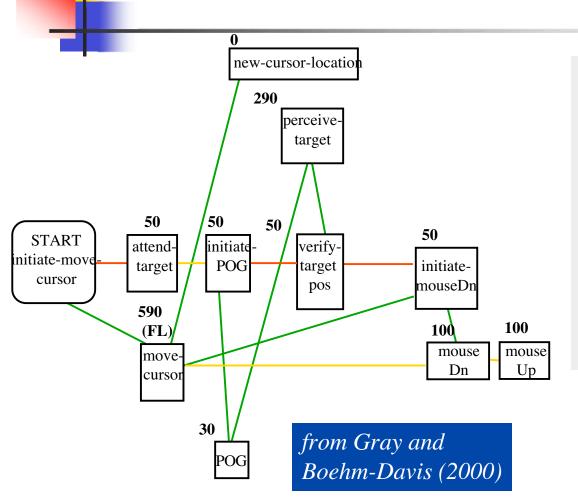
Mozilla

AMBR (HLA) (+ Sherpa)

Reusable effort:
Apex API
Sim compatibility
Com support



Resuable building-blocks



(index (fast-move-click-R-hand-on-mouse :target ?target)) (step c1 (initiate-move-cursor ?target)) (step m1 (move-cursor ?target) (waitfor ?c1)) (step c2 (attend-target ?target)) (step c3 (initiate-eye-movement ?target) (waitfor ?c2)) (step m2 (eye-movement ?target) (waitfor ?c3)) (step p1 (perceive-target-complex ?target)) (step c4 (verify-target-position ?target) (waitfor ?c3 ?p1)) (step c5 (initiate-click ?target) (waitfor ?c4 ?m1)) (step m3 (mouse-down ?target) (waitfor ?m1 ?c5)) (step m4 (mouse-up ?target) (waitfor ?m3)) (step t (terminate) (waitfor ?m4 ?rvr1 ?rvr2)))





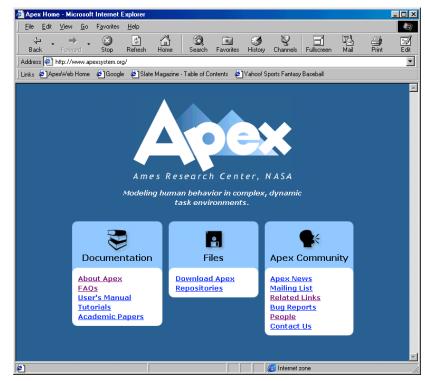
Distributed Development

Why needed

- Library of "building blocks"
- Resource models
- Software interfaces
- Visualization tools

Making it happen

- Software infrastructure
- Educational outreach
- Web-based support



Apex collaborative web site (CMU HCI project 2001)